Dynamics of magnetic solitons in ³He-B

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The production and propagation of n-texture solitons in the B phase of 3 He in a magnetic field is analyzed. It is conceivable that n solitons were observed in 3 He-B by Webb, Sager, and Wheatley 3 in their experiments after the magnetic field was turned off.

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As Maki and Kumar have shown, the presence of a magnetic field in 3 He-B, whose condensate is described in terms of the unit vector \mathbf{n} and the angle θ , leads to the formation of \mathbf{n} textures that are analogous to the magnetic walls in nematics. In this paper we examine the production and propagation of \mathbf{n} solitons after the non-uniform magnetic field has been turned off. In a similar case Webb, Sager, and Wheatley observed the propagation of slow magnetic perturbations in He-B, whose velocity depends on the exciting magnetic field in a complicated way. To identify the magnetic perturbations with \mathbf{n} solitons, which were observed in Ref. 3 and investigated in this work, we must measure the dependence of the wave's velocity on the magnetic fields in greater detail; however, the results of Ref. 3 can be explained qualitatively in terms of \mathbf{n} solitons.

We examine the Lagrangian function L = T - U in ³ He-B in a magnetic field H. The potential energy U is comprised of the gradient energy⁴

$$F_B = \int d\mathbf{r} \{ K_1 (\text{div } \mathbf{n})^2 + K_2 (\mathbf{n} \text{ rot } \mathbf{n})^2 + K_3 (\mathbf{n} \text{ rot } \mathbf{n})^2 - K_4 \text{ div } \mathbf{n} (\mathbf{n} \text{ rot } \mathbf{n}) \}$$
 (1)

and the orientational energy in a magnetic field4

$$F_{\mathbf{H}} = -a \int d\mathbf{r} \, (\mathbf{nH})^2, \tag{2}$$

where $K_i = (b_i/64)\hbar^2 \rho_s/m$, $b_1 = 13$, $b_2 = 11$, $b_3 = 16$, $b_4 = 13\sqrt{15/8}$, ρ_s is the superfluid density, and m is the mass of an ³He atom; the expression for a is given by Eq. (6) taken from Ref. 4. Equation (1) corresponds to Leggett's configuration (cos $\theta = -1/4$), since the dipole energy greatly exceeds F_H over a broad range of magnetic fields. The kinetic energy is ¹

$$T = \frac{\chi_B}{2\gamma_o^2} \int d\mathbf{r} \left[\left(\vec{\omega} - \vec{\omega}_o \right)^2 - \vec{\omega}_o^2 \right], \tag{3}$$

where χ_B is the susceptibility of ³He-B and γ_0 is the gyromagnetic ratio of ³He nuclei.

$$\vec{\omega}_{o} = \gamma_{o} H$$
, $\vec{\omega} = -\frac{5}{4} n \times n_{t} + \frac{\sqrt{15}}{4} n_{t}$, $\theta = \theta_{o}$.

We can now easily obtain an equation of motion for the **n** vector. We confine ourselves to analyzing the planar textures. We assume that the magnetic field is directed along the x axis and $\mathbf{n} = \{\cos\phi(x), \sin\phi(x), 0\}$. This case, which pertains to splay-bend deformations, is described by the equation

$$\phi_{tt} - c_3^2 \phi_{xx} + \frac{c_3^2}{2\xi_{H_3} \phi_{u}} \frac{\partial}{\partial x} \left[\sin^2 \phi \left(1 + a^2 \xi_{H_3}^2 \phi_x^2 \right) \right] = 0, \quad (4)$$

where

$$c_i^2 = \frac{b_i}{80} \frac{\gamma_o^2}{\chi_B} \frac{\hbar^2 \rho_s}{m}, \ \xi_{Hi} = \frac{1}{H} \left(\frac{K_i}{a}\right)^{1/2}, \ \alpha^2 = 1 - \frac{b_1}{b_3} = \frac{3}{16}.$$

Note that if $K_1 = K_3$ ($\alpha^2 = 0$), then the static solution of Eq. (4) will represent a wall that is perpendicular to the magnetic field.² The anisotropy $(K_1 \neq K_3)$ causes the wall to become an asymmetric plane x = 0.

If the solution of Eq. (4) is sought in the form of a traveling wave: $\phi = \phi(x - ut)$, then we obtain the condition

$$\frac{u^2}{c_3^2} << \frac{b_1}{b_3} \approx 1. \tag{5}$$

If this condition is satisfied, then we can ignore the difference between K_1 and K_3 and solve the equation

$$\phi_{t,t} - c^2 \phi_{xx} + \Omega_H^2 \sin \phi \cos \phi = 0 \tag{6}$$

instead of Eq. (4). Here,

$$c_1 = c_3 = c$$
, $\Omega_H^2 = \gamma^2 H^2$, $\gamma^2 = \frac{4}{5} \frac{a \gamma_o^2}{\chi_R}$.

We now describe the case in which the additional, nonuniform, magnetic field $H_0(x)$ is turned off. We define the initial conditions for Eq. (6)

$$t = 0, \ \phi = 0, \ \phi_t = \delta \gamma_0 H_0(x) , \qquad (7)$$

where δ is a constant that is determined experimentally. After substituting $2\phi = \psi$ and converting to dimensional variables $\tau = \Omega_{\mathbf{H}} t$ and $\xi = \Omega_{\mathbf{H}} x/c$, we obtain a standard sine-Gordon equation,

$$\psi_{\tau\tau} - \psi_{\xi\xi} + \sin\psi = 0 \tag{8}$$

with the initial conditions

$$\tau = 0, \quad \psi = 0, \quad \psi_{\tau} = 2 \omega \left(\xi \right). \tag{9}$$

We select $\omega(\xi)$ in the form used by Maki and Kumar⁵ for the investigation of the dynamics of solitons in ³ He-A by using the inverse-scattering method that was developed by Ablowitz *et al.*⁶ for the sine-Gordon equation

$$\omega(\xi) = \omega\theta(l^2 - \xi^2), \tag{10}$$

where $l=L/\xi_H$, $\omega = \delta \gamma_0 H_0/\gamma H$, 2L is the "length" of the pulse, and H_0 is the strength of the magnetic field that is turned off. We can use in this case the results of Ref. 5. To produce N pairs of solitons or pulsating (breather) modes, 6 the following inequality must be satisfied⁵:

$$I \Rightarrow I_N$$
 (11)

Here,

$$I = l\omega$$
, $I_N = \pi \left(N - \frac{1}{2}\right)$, $N = 1, 2, ...$

The soliton pairs can be formed provided that⁵

$$\omega > \omega_N$$
 (12)

(the inverse inequality corresponds to the pulsating (breather) modes). The dependence of ω_N on I was determined numerically⁵; however, we can easily obtain for ω_N the following analytic expression:

$$\omega_N = \frac{1 + I^2}{I(1 + I^2 - I_N^2)^{1/2} - I_N}, \qquad (13)$$

which contains a small inaccuracy only when $\omega_N \to 1$. Finally, the velocity of Nth soliton is

$$u_N = c \left(1 - \frac{\omega_N^2}{\omega^2}\right)^{1/2}. \tag{14}$$

We shall briefly consider the dependence of the velocity of a soliton on the temperature T and on the fields H_0 and H. The temperature dependence of the maximum velocity c of a soliton $\propto \rho_S^{1/2} \propto (1-T/T_c)^{1/2}$ (here the dependence of χ_B on T is disregarded) coincides with the temperature dependence of the rate of magnetic perturbations observed in Ref. 3. This rate is approximately three to four times smaller then c; moreover, the rate of magnetic perturbations increases with decreasing magnetic field H_M and increasing H_R field. According to Eq. (14), the velocity of an c soliton has similar dependences on the fields c and c which correspond to c and c and c and c when the dependence on c and c and c determined primarily by the quantity c and when the dependence on c and c determined primarily by the quantity c and which is given by Eq. (14), is stronger than that observed in Ref. 3 if the "experimental" temperature dependence of the quantity c is taken into account, in accordance with Ref. 4.

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